

# Math 110, Summer 2012 Short Homework 5 (SOME) SOLUTIONS

Due Thursday 7/5, 10.10am, in Etcheverry 3109. Late homework will not be accepted.

## Calculations

1. Consider the bases

$$\mathcal{S}^{(2)} = (e_1, e_2) \subset \mathbb{Q}^2, \mathcal{C} = (f_1, f_2, f_3) \subset \mathbb{Q}^{\{1,2,3\}},$$

where

$$f_1(1) = 1, f_1(2) = 0, f_1(3) = -1; f_2(1) = 0, f_2(2) = -1, f_2(3) = -1; f_3(1) = 1, f_3(2) = 2, f_3(3) = 0.$$

Consider the following linear morphism

$$\alpha : \mathbb{Q}^2 \rightarrow \mathbb{Q}^{\{1,2,3\}}; \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \mapsto \alpha \left( \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \right) = f : \begin{cases} 1 \mapsto x_1 \\ 2 \mapsto x_2 \\ 3 \mapsto x_1 + x_2 \end{cases}.$$

Determine  $[\alpha]_{\mathcal{S}^{(2)}}^{\mathcal{C}}$ . Is  $\alpha$  injective? Explain your answer. What is  $[\alpha]_{\mathcal{S}^{(2)}}^{\mathcal{B}}$ , where  $\mathcal{B} = \{e_i \mid i = 1, 2, 3\} \subset \mathbb{Q}^{\{1,2,3\}}$ ?

(To determine  $[\alpha]_{\mathcal{S}^{(2)}}^{\mathcal{C}}$  you will need to find the  $\mathcal{C}$ -coordinates of  $\alpha(e_i)$  - to do this it may help to use the change of coordinate matrix  $P_{\mathcal{C} \leftarrow \mathcal{B}} = P_{\mathcal{B} \leftarrow \mathcal{C}}^{-1}$ .)

*Solution:* Using the properties of associating matrices to morphisms we have

$$[\alpha]_{\mathcal{S}^{(2)}}^{\mathcal{C}} = [\text{id}_{\mathbb{Q}^{\{1,2,3\}}} \circ \alpha]_{\mathcal{S}^{(2)}}^{\mathcal{C}} = [\text{id}_{\mathbb{Q}^{\{1,2,3\}}}]_{\mathcal{B}}^{\mathcal{C}} [\alpha]_{\mathcal{S}^{(2)}}^{\mathcal{B}} = P_{\mathcal{C} \leftarrow \mathcal{B}} [\alpha]_{\mathcal{S}^{(2)}}^{\mathcal{B}}.$$

Then, we have

$$[\alpha]_{\mathcal{S}^{(2)}}^{\mathcal{B}} = [[\alpha(e_1)]_{\mathcal{B}} [\alpha(e_2)]_{\mathcal{B}}] = \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 1 & 1 \end{bmatrix},$$

and

$$P_{\mathcal{B} \leftarrow \mathcal{C}} = \begin{bmatrix} 1 & 0 & 1 \\ 0 & -1 & 2 \\ -1 & -1 & 0 \end{bmatrix}.$$

Then, we find that

$$P_{\mathcal{C} \leftarrow \mathcal{B}} = P_{\mathcal{B} \leftarrow \mathcal{C}}^{-1} = \begin{bmatrix} 2 & -1 & 1 \\ -2 & 1 & -2 \\ -1 & 1 & -1 \end{bmatrix}.$$

Hence, we have

$$[\alpha]_{\mathcal{S}^{(2)}}^{\mathcal{C}} = P_{\mathcal{C} \leftarrow \mathcal{B}} [\alpha]_{\mathcal{S}^{(2)}}^{\mathcal{B}} = \begin{bmatrix} 2 & -1 & 1 \\ -2 & 1 & -2 \\ -1 & 1 & -1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 1 & 1 \end{bmatrix} = \begin{bmatrix} 3 & 0 \\ -4 & -1 \\ -2 & 0 \end{bmatrix}.$$

We see that  $\alpha$  is injective since there is a pivot in every column of  $[\alpha]_{\mathcal{S}^{(2)}}^{\mathcal{B}}$  (or  $[\alpha]_{\mathcal{B}}^{\mathcal{C}}$ , either will do).

2. Consider the matrix

$$A = \begin{bmatrix} 1 & -1 & 2 \\ 0 & 1 & 1 \end{bmatrix} \in \text{Mat}_{2,3}(\mathbb{Q}).$$

Determine the rank of  $A$ ,  $\text{rank } A = r$ , and find matrices  $P \in \text{GL}_3(\mathbb{Q})$ ,  $Q \in \text{GL}_2(\mathbb{Q})$  such that

$$Q^{-1}AP = \begin{bmatrix} I_r & 0_{r,3-r} \\ 0_{2-r,r} & 0_{2-r,3-r} \end{bmatrix}.$$

(Of course, if  $r = 2$  then we do not have the bottom row. You need to replicate your proof of Q4.)

*Solution:* We have  $\text{rank } A = \dim \text{im } T_A$  and since

$$Ae_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}, Ae_2 = \begin{bmatrix} -1 \\ 1 \end{bmatrix} \in \text{im } T_A,$$

and these vectors are linearly independent, we must have  $\text{im } T_A = \mathbb{Q}^2$  (we have just shown that  $\text{im } T_A$  is at least 2 dimensional, since it's a subspace of a 2 dimensional space it must be the whole space). Hence,  $\text{rank } A = 2$ .

There are many ways to proceed to find  $P, Q$  - you can use elementary matrices or the following procedure: we find a basis for  $\ker T_A \subset \mathbb{Q}^3$ . By row-reducing  $A$  we see that any solution  $\underline{x}$  such that  $A\underline{x} = \underline{0}$  must take the form

$$\underline{x} = \begin{bmatrix} -3c \\ -c \\ c \end{bmatrix}, \text{ for some } c \in \mathbb{Q}.$$

Now, extend the basis

$$\mathcal{B} = \left( \begin{bmatrix} -3 \\ -1 \\ 1 \end{bmatrix} \right),$$

of  $\ker T_A$  to a basis  $\mathcal{B}$  of  $\mathbb{Q}^3$ . For example, we can extend to

$$\mathcal{B} = \left( \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -3 \\ -1 \\ 1 \end{bmatrix} \right).$$

Then,

$$c' = \left( A \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, A \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \right) = \left( \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 1 \end{bmatrix} \right),$$

is a basis of  $\text{im } T_A$ . Since  $\text{im } T_A = \mathbb{Q}^2$  we don't need to extend to a basis of  $\mathbb{Q}^2$  so that we can take

$$Q = \begin{bmatrix} 1 & -1 \\ 0 & 1 \end{bmatrix}, P = \begin{bmatrix} 1 & 0 & -3 \\ 0 & 1 & -1 \\ 0 & 0 & 1 \end{bmatrix}$$

and we have

$$Q^{-1}AP = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}.$$

3. Let  $\mathcal{S}^{(3)} = \{e_1, e_2, e_3\}$  be the standard basis of  $\mathbb{Q}^3$ . There are six possible orderings of  $\mathcal{S}^{(3)}$ : write them all down to obtain six different ordered bases  $\mathcal{B}_1, \dots, \mathcal{B}_6$  and so that  $\mathcal{B}_1 = (e_1, e_2, e_3)$ . Write down the change of coordinates matrices  $P_{\mathcal{B}_i \leftarrow \mathcal{B}_1}$ , for  $i = 1, \dots, 6$ .

### Proofs

4. Let  $f, g \in \text{Hom}_{\mathbb{K}}(V, W)$ ,  $\mathcal{B} = \{b_1, \dots, b_n\} \subset V$  a basis of  $V$ . Prove that if  $f(b_i) = g(b_i)$ , for each  $i = 1, \dots, n$ , then  $f = g$ .

(In order to show that two functions  $f, g : V \rightarrow W$  are equal, you must show that  $f(v) = g(v)$ , for every  $v \in V$ . Therefore, this questions tells us that in order to show two linear morphisms are equal, it suffices to check that they are equal on a basis.)

*Solution:* Let  $v \in V$ . Then, since  $\mathcal{B}$  is a basis of  $V$  we have

$$v = \lambda_1 b_1 + \dots + \lambda_n b_n,$$

so that

$$\begin{aligned} f(v) &= f(\lambda_1 b_1 + \dots + \lambda_n b_n) \\ &= \lambda_1 f(b_1) + \dots + \lambda_n f(b_n) \\ &= \lambda_1 g(b_1) + \dots + \lambda_n g(b_n) \\ &= g(\lambda_1 b_1 + \dots + \lambda_n b_n) = g(v). \end{aligned}$$

Hence, we see that  $f = g$ .

5. Let  $A \in \text{Mat}_{m,n}(\mathbb{K})$  be such that  $\text{rank } A = r$ . Prove that there exists  $P \in \text{GL}_n(\mathbb{K}), Q \in \text{GL}_m(\mathbb{K})$  such that

$$Q^{-1}AP = \begin{bmatrix} I_r & 0_{r,n-r} \\ 0_{m-r,r} & 0_{m-r,n-r} \end{bmatrix}.$$

(Replicate the proof of Theorem 1.7.14 for  $f = T_A$ . How do  $P, Q$  arise?)

*Solution:* Take a basis  $\mathcal{B}' = (b_{r+1}, \dots, b_n)$  of  $\ker T_A$  and extend to a basis  $\mathcal{B}$  of  $\mathbb{K}^n$ , say

$$\mathcal{B} = (b_1, \dots, b_r, b_{r+1}, \dots, b_n).$$

Then, as in the proof of the Rank Theorem we see that

$$\mathcal{C}' = (Ab_1, \dots, Ab_r),$$

is a basis of  $\text{im } T_A$ . Now, extend this to a basis

$$\mathcal{C} = (Ab_1, \dots, Ab_r, c_{r+1}, \dots, c_m),$$

of  $\mathbb{K}^m$ . Now, let

$$P = [b_1 \ \dots \ b_n], \quad Q = [Ab_1 \ \dots \ c_m].$$

The result follows by relating that matrix of  $T_A$  with respect to  $\mathcal{B}$  and  $\mathcal{C}$  and the matrix of  $T_A$  with respect to the standard bases.