

# Math 255 Lectures: 6.1, 6.2

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## 6.1: Holomorphic differentials

Given a lattice  $\Lambda$  in  $\mathbb{C}$ , we have associated a nonsingular cubic curve  $C_\Lambda$  in  $\mathbb{P}_2$  defined by the equation

$$y^2z = 4x^3 - g_2(\Lambda)xz^2 - g_3(\Lambda)z^3.$$

Now, we wish to know whether given a curve  $C_\Lambda$ , can we recover the lattice  $\Lambda$ ? In order to do this, we now introduce some new concepts.

**Definition 1.** A **piecewise smooth path** in a Riemann surface  $S$  is a continuous map  $\gamma$  from a closed interval  $[a, b] \subset \mathbb{R}$  to  $S$  such that if  $\phi : U \rightarrow V$  is a holomorphic chart on an open subset  $U$  of  $S$  and  $[c, d] \subset \gamma^{-1}(U)$  then

$$\phi \circ \gamma : [c, d] \rightarrow V$$

is a piecewise smooth path in  $V \subset \mathbb{C}$ . The path is **closed** if  $\gamma(a) = \gamma(b)$ .



**Definition 2.** A **meromorphic function** on a Riemann surface  $S$  is a function  $f : S \rightarrow \mathbb{P}_1$  which is holomorphic (in the sense of Riemann surfaces) and is not identically  $\infty$  on any connected component of  $S$ .

**Remark 3.** A holomorphic function  $f : S \rightarrow \mathbb{C}$  on a compact Riemann surface  $S$  is a constant. However, there are many interesting meromorphic functions  $f : S \rightarrow \mathbb{P}_1$ .

**Example 4.** Let  $C$  be an irreducible projective curve defined by  $P[x, y, z] = 0$ . By a **rational function** on  $C - \text{Sing}(C)$ , we mean a meromorphic function on  $C - \text{Sing}(C)$  of the form

$$[x : y : z] \mapsto \frac{S(x, y, z)}{T(x, y, z)}$$

where  $S$  and  $T$  are homogeneous polynomials **of the same degree** and  $T$  does not vanish everywhere on  $C$ . If  $S$  and  $T$  both have degree  $k$ , then

$$\frac{S(\lambda x, \lambda y, \lambda z)}{T(\lambda x, \lambda y, \lambda z)} = \frac{\lambda^k S(x, y, z)}{\lambda^k T(x, y, z)}$$

so the function is well-defined.

Now, we will introduce meromorphic differentials, which we plan to integrate later.

**Definition 5.** Let  $f$  and  $g$  be meromorphic functions on a Riemann surface  $S$ . Then we say that

$$f \, dg$$

is a **meromorphic differential** on  $S$ , and if  $f'$  and  $g'$  are also meromorphic functions on  $S$ , we say that

$$f \, dg = f' \, dg'$$

if for every holomorphic chart  $\phi : U \rightarrow V$  we have

$$(f \circ \phi^{-1})(g \circ \phi^{-1})' = (f' \circ \phi^{-1})(g' \circ \phi^{-1})'.$$

**Remark 6.** There are some technical comments in the book following this definition, including an alternative definition of “meromorphic differential”. We skip this now in the interest of time.

**Definition 7.** We say that the meromorphic differential  $f dg$  has a pole at a point  $p$  in  $S$  if whenever  $\phi : U \rightarrow V$  is a holomorphic chart on  $U \ni p$ , we have that  $\phi(p)$  is a pole of the meromorphic function  $(f \circ \phi^{-1})(g \circ \phi^{-1})'$ . We call  $f dg$  a **holomorphic differential** if it has no poles.

As promised, we now integrate.

**Definition 8.** If  $f dg$  is a holomorphic differential on  $S$  then the integral of  $f dg$  along a piecewise-smooth path  $\gamma : [a, b] \rightarrow S$  is

$$\int_{\gamma} f dg = \int_a^b (f \circ \gamma(t)) \cdot (g \circ \gamma)'(t) dt$$

Then, one must check that this is well-defined up to equivalence of holomorphic differentials (if this interests you see Remark 6.12).

**Remark 9.** If we re-parametrize the path (i.e., give a map  $\phi : [c, d] \rightarrow [a, b]$  which is piecewise smooth) then the integral along  $\gamma \circ \phi$  equals the integral along  $\gamma$  (checked explicitly in remark 6.13).

**Example 10.** If the Riemann surface  $S$  is  $\mathbb{C}$ , then

$$\int_{\gamma} f dg = \int_{\gamma} f(x)g'(x) dz$$

is the integral of  $f(z)g'(z)$  along  $\gamma$  in the usual sense of complex analysis.

**Example 11.** If  $g : S \rightarrow \mathbb{C}$  is a holomorphic mapping on any Riemann surface  $S$  then

$$\int_{\gamma} dg = g(\gamma(b)) - g(\gamma(a)).$$

**Definition 12.** If  $\psi : S \rightarrow R$  is a holomorphic mapping between Riemann surfaces  $S$  and  $R$ , and if  $f dg$  is a holomorphic differential on  $R$  then we define a holomorphic differential  $\psi^*(f dg)$  on  $S$  by

$$\psi^*(f dg) = (f \circ \psi)d(g \circ \psi).$$

Then If  $\gamma : [a, b] \rightarrow S$  is a piecewise-smooth path in  $S$  we have

$$\int_{\gamma} \psi^*(f dg) = \int_a^b (f \circ \psi \circ \gamma(t))(g \circ \psi \circ \gamma)'(t) dt = \int_{\psi \circ \gamma} f dg.$$

Let  $C$  be an irreducible projective curve in  $\mathbb{P}_2$  defined by a polynomial  $P$ . An **abelian integral** is an integral of the form

$$\int_{\gamma} f dg$$

where  $f$  and  $g$  are rational functions on  $C - \text{sing}(C)$  and  $\gamma$  is a piecewise-smooth path in  $C - \text{sing}(C)$  not passing through any poles of the meromorphic differential  $f dg$ .

We usually assume that  $C$  is not the line at infinity defined by  $z = 0$  and take the function  $g$  to be

$$[x : y : z] \mapsto \frac{x}{z}.$$

We often then work in the affine coordinates  $[x : y : 1]$  and write  $dx$  for  $dg$ . In affine coordinates  $f$  becomes a rational function  $R(x, y)$  of  $x$  and  $y$  in the usual sense, and our integral is written

$$\int_{\gamma} f dg = \int_{\gamma} R(x, y) dx,$$

where we now regard  $y$  as a multivalued function of  $x$  via the equation  $P(x, y, 1)$  which defines  $C$  in affine coordinates.

The integral is called an **elliptic integral** if  $C$  is an elliptic curve, meaning it is defined by an equation

$$y^2 = (x - \alpha_1) \cdots (x - \alpha_k),$$

where  $k = 3, 4$ . If  $k$  is larger then  $C$  is called a **hyperelliptic curve** and the integral  $\int_{\gamma} f dg$  is called a **hyperelliptic integral**.

Recall our lattice  $\Lambda \subset \mathbb{C}$  and biholomorphism  $u : \mathbb{C}/\Lambda \rightarrow C_{\Lambda}$ . We have a meromorphic differential on  $C_{\Lambda}$  given in homogeneous coordinates  $[x, y, 1]$  by  $y^{-1} dx$ . Let

$$\eta = u * (y^{-1} dx).$$

Then  $\eta$  is a meromorphic differential on  $\mathbb{C}/\Lambda$ . Moreover, we will show it is holomorphic. If

$$\pi : \mathbb{C} \rightarrow \mathbb{C}/\Lambda$$

is given by  $\pi(z) = \Lambda + z$  then

$$\pi * \eta = \pi * u * (y^{-1} dx) = (u \circ \pi) * (y^{-1} dx) = (p')^{-1} dp = (p')^{-1} p' dz = dz,$$

where  $x : \mathbb{C} \rightarrow \mathbb{C}$  denotes the identity function, and  $p(z)$  is the function used in defining  $u$  from 2 lectures ago. Since  $\pi$  is locally a holomorphic bijection with holomorphic inverse and  $dz$  is a holomorphic differential on  $\mathbb{C}$  it follows that  $\eta$  has no poles, so  $\eta$  is a holomorphic differential on  $\mathbb{C}/\Lambda$ . Since  $u$  is a holomorphic bijection with holomorphic inverse it follows that  $y^{-1} dx$  is a holomorphic differential on  $C_\Lambda$ .

Let  $\lambda \in \Lambda$  and define a path  $\gamma' : [0, 1] \rightarrow \mathbb{C}$  by  $t \mapsto t\lambda$ . If  $\gamma = \pi \circ \gamma'$ , then  $\gamma(t) = \Lambda + t\lambda$ , so  $\gamma(0) = \gamma(1)$ . Hence,  $\gamma$  is a piecewise smooth closed path in  $\mathbb{C}/\Lambda$ . Then,

$$\int_\gamma \eta = \int_{\gamma'} \pi^* \eta = \int_{\gamma'} dz = \gamma'(1) - \gamma'(0) = \lambda.$$

Given any  $\gamma : [a, b] \rightarrow \mathbb{C}/\Lambda$  is any piecewise smooth closed path then (by appendix lemma) we can find a continuous path  $\gamma' : [a, b] \rightarrow \mathbb{C}$  so that  $\pi \circ \gamma' = \gamma$  which is also piecewise smooth. Then,

$$\int_\gamma \eta = \int_{\gamma'} \pi^* \eta = \int_{\gamma'} dz = \gamma'(b) - \gamma'(a) \in \Lambda.$$

We have proved:

**Proposition 13.**

$$\Lambda = \left\{ \int_\gamma \eta \mid \gamma \text{ is a closed piecewise smooth path in } \mathbb{C}/\Lambda \right\}.$$

**Corollary 14.**

$$\Lambda = \left\{ \int_\gamma y^{-1} dx \mid \gamma \text{ is a closed piecewise smooth path in } C_\Lambda \right\}.$$

**Hence, we can recover the lattice from the curve  $C_\Lambda$  in  $\mathbb{P}_2$ .**

Now we are also prepared to describe  $u^{-1}$ .

**Proposition 15.** *The inverse of  $u$  is given by*

$$u^{-1}(p) = \Lambda + \int_{[0:1:0]}^p y^{-1} dz$$

(note: this makes sense because if we have two paths from  $[0 : 1 : 0]$  to  $p$  then the difference of their integrals will be an integral over a closed path and hence an element of  $\Lambda$ .)

## 6.2 Abel's Theorem

**Last lecture:** we saw that any complex torus  $\mathbb{C}/\Lambda$  is biholomorphic to a nonsingular curve  $C_\Lambda$  in  $\mathbb{P}^2$

**Today:** We study the abelian group structure. The torus  $\mathbb{C}/\Lambda$  is an abelian group under addition. This gives the cubic curve  $C_\Lambda$  an induced abelian group structure.

This can be described completely in terms of the geometry of the curve  $C_\Lambda$  and it is determined by two properties:

1. The identity element is  $[0 : 1 : 0]$  (the inflection point).
2. Three points  $p, q, r$  add to zero if and only if they are the three points of intersection of the cubic with a line.

**Remark 16.** We have already seen (Section 3) that if  $p_0$  is an inflection point on a nonsingular projective cubic  $C$  then there is a unique additive group structure on  $C$  satisfying (1) and (2) above. Then, we can view Abel's theorem as the statement that the holomorphic bijection

$$u : \mathbb{C}/\Lambda \rightarrow C_\Lambda$$

is actually a group isomorphism with respect to this group structure on  $C_\Lambda$  and the quotient group structure on  $\mathbb{C}/\Lambda$ .

**Remark 17.** Recall from earlier that a line in  $\mathbb{P}_2$  meets a nonsingular cubic curve  $C$  in either (**QUIZ**):

1. 3 distinct points with multiplicity 1 (3 ordinary intersection points)
2. 2 distinct points with one having multiplicity 1 and one having multiplicity 2 (one ordinary intersection point and one tangent)
3. one point with multiplicity 3 (line is tangent at inflection point)

So for the group, this means that

1. three distinct points  $p + q + r = 0$  iff  $p, q, r$  are distinct points on a line in  $\mathbb{P}^2$ ;
2. two points  $2p + q = 0$  iff the tangent to  $C_\Lambda$  at  $p$  passes through  $q$ ;
3. and  $3p = 0$  iff  $p$  is a point of inflection.

From this last comment we see that the points of order 1 or 3 are **precisely** the inflection points on  $C_\Lambda$ . Under the group isomorphism  $u : \mathbb{C}/\Lambda \rightarrow C_\Lambda$  we see that there are exactly 9 such points in  $\mathbb{C}/\Lambda$ , and they can be written in the form

$$\Lambda + \frac{j}{3}\omega_1 + \frac{k}{3}\omega_2$$

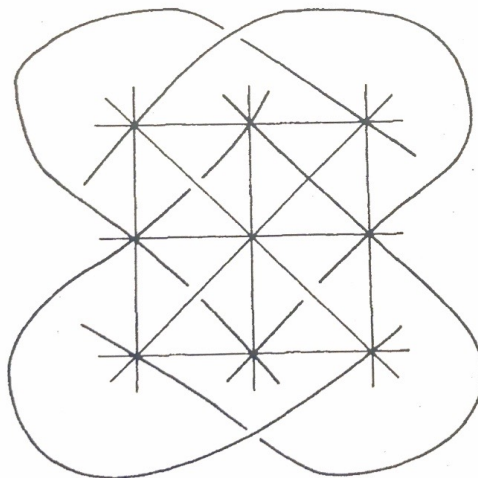
where  $j, k \in \{0, 1, 2\}$ .

These points form a subgroup of  $\mathbb{C}/\Lambda$  isomorphic to  $\mathbb{Z}_3 \times \mathbb{Z}_3$ . The three entries in any row, column, or diagonal add up to  $\Lambda + 0$ : It follows that  $C_\Lambda$  has exactly

$\Lambda + 0$	$\Lambda + \frac{1}{3}\omega_2$	$\Lambda + \frac{2}{3}\omega_2$
$\Lambda + \frac{1}{3}\omega_1$	$\Lambda + \frac{1}{3}\omega_1 + \frac{1}{3}\omega_2$	$\Lambda + \frac{1}{3}\omega_1 + \frac{2}{3}\omega_2$
$\Lambda + \frac{2}{3}\omega_1$	$\Lambda + \frac{2}{3}\omega_1 + \frac{1}{3}\omega_2$	$\Lambda + \frac{2}{3}\omega_1 + \frac{2}{3}\omega_2$

9 inflection points.

The following collections of these points on  $C_\Lambda$  all lie on lines in  $\mathbb{P}_2$ :



Recall from the end of the previous lecture that the inverse of  $u$  is given by

$$u^{-1}(p) = \Lambda + \int_{[0:1:0]}^p y^{-1} dx,$$

where the integral is over any piecewise smooth path in  $C_\Lambda$  from  $[0 : 1 : 0]$  to  $p$ .

**Theorem 18** (Abel's Theorem). *If  $t, v, w \in \mathbb{C}$  then*

$$t + v + w \in \Lambda$$

*if and only if there is a line  $L$  in  $\mathbb{P}_2$  whose intersection with  $C_\Lambda$  consists of the points  $u(\Lambda + t)$ ,  $u(\Lambda + v)$ , and  $u(\Lambda + w)$  (allowing for multiplicities).*

*Equivalently, if  $p, q, r \in C_\Lambda$  then*

$$\Lambda + \int_{[0:1:0]}^p y^{-1} dx + \int_{[0:1:0]}^q y^{-1} dx + \int_{[0:1:0]}^r y^{-1} dx = \Lambda + 0$$

*if and only if  $p, q, r$  are the points of intersection with a line in  $\mathbb{P}_2$ .*

**Remark 19.** We can interpret Abel's theorem as an addition formula modulo  $\Lambda$  for integrals of the form

$$\int_{[0:1:0]}^p y^{-1} dx$$

on  $C_\Lambda$ .

For the rest of the talk we will prove Abel's Theorem.

*Proof.* First we show that if  $L$  is a line in  $\mathbb{P}_2$ , then

$$\Lambda + \int_{[0:1:0]}^p y^{-1} dx + \int_{[0:1:0]}^q y^{-1} dx + \int_{[0:1:0]}^r y^{-1} dx = \Lambda + 0$$

We do this in 3 increasingly general cases.

**Case 1:** Suppose  $L$  is the tangent line  $z = 0$  to  $C_\Lambda$  at the point of inflection  $[0 : 1 : 0]$ . Then  $p = q = r$ , so the equality we wish to prove is trivial.

**Case 2:** Suppose that  $L$  is a line of the form  $cy = bz$ . Then  $L$  meets  $C_\Lambda$  in 3 points:

$$p_1(b, c) = [a_1, b, c]$$

$$p_2(b, c) = [a_2, b, c]$$

$$p_3(b, c) = [a_3, b, c]$$

where  $a_1, a_2, a_3$  are the roots of the polynomial

$$Q_\Lambda(x, b, c) = b^2c - 4x^3 + g_2(\Lambda)xc^2 + g_3(\Lambda)c^3.$$



Define a map  $\mu : \mathbb{P}_1 \rightarrow \mathbb{C}/\Lambda$  by

$$\mu[b, c] = \Lambda + \int_{[0:1:0]}^{p_1(b,c)} y^{-1} dx + \int_{[0:1:0]}^{p_2(b,c)} y^{-1} dx + \int_{[0:1:0]}^{p_3(b,c)} y^{-1} dx$$

where the integrals are over any paths in  $\mathbb{C}$ . This map  $\mu$  is well defined. We now give two lemmas.

**Lemma 20.**  $\mu : \mathbb{P}_1 \rightarrow \mathbb{C}$  is holomorphic.

**Lemma 21.** Any holomorphic map from  $\mathbb{P}_1$  to  $\mathbb{C}$  is constant.

The proof of the first lemma will be given when the proof of Abel's theorem is complete. The second lemma is clear by homework exercises:  $\mathbb{P}_1$  is compact so its image under a holomorphic map to  $\mathbb{C}$  is a constant.

By the appendix Lemma there is a continuous map  $\tilde{\mu} : \mathbb{P}_1 \rightarrow \mathbb{C}$  such that  $\mu = \pi \circ \tilde{\mu}$ . Since the inverse of the restriction of  $\pi$  to a suitable open neighborhood of any  $a \in \mathbb{C}$  defines a holomorphic chart on a neighborhood of  $\Lambda + a$  in  $\mathbb{C}/\Lambda$  and  $\mu$  is holomorphic, it follows that  $\tilde{\mu}$  is holomorphic. By the second lemma, it is therefore a constant. Thus  $\mu$  is a constant map.

By case 1,  $\mu[1, 0] = \Lambda + 0$ , so we have that  $\mu[b, c] = \Lambda + 0$  for all  $[b, c] \in \mathbb{P}_1$ .

**Case 3:** Suppose now that  $L$  is any line in  $\mathbb{P}_2$ . Then the equation for  $L$  can be written in the form

$$sx + t(cy - bz) = 0,$$

for some  $s, t$  not both zero and  $b, c$  both not zero. Fix  $b, c$  and define a map  $\nu : \mathbb{P}_1 \rightarrow \mathbb{C}/\Lambda$  by

$$\nu[s, t] = \Lambda + \int_{[0:1:0]}^{q_1(s,t)} y^{-1} dx + \int_{[0:1:0]}^{q_2(s,t)} y^{-1} dx + \int_{[0:1:0]}^{q_3(s,t)} y^{-1} dx$$

where  $q_1(s, t), q_2(s, t), q_3(s, t)$  are the points of intersection of  $C_\Lambda$  with the line  $sx + t(cy - bz) = 0$ .

As in case 2 this map  $\nu$  is holomorphic and hence constant. From case 2 we also know that  $\nu[0, 1] = \Lambda + 0$  so for all  $[s, t] \in \mathbb{P}_1$  we have  $\nu[s, t] = \Lambda + 0$ . This completes one direction of the proof up to the unproven lemma.

Conversely, suppose that  $t, v, w \in \mathbb{C}$  and  $t + v + w \in \Lambda$ . Let

$$p = u(\Lambda + t), \quad q = u(\Lambda + v), \quad r = u(\Lambda + w).$$

Let  $L$  be the line through  $p, q$  or tangent at  $p = q$  if that is the case. Then,  $L$  meets  $C_\Lambda$  in  $p, q$  and another point  $\tilde{r}$ . Then by what we have just proved,

$$\begin{aligned} u^{-1}(p) + u^{-1}(q) + u^{-1}(\tilde{r}) &= \Lambda + 0 \\ &= \Lambda + t + v + w \\ &= u^{-1}(p) + u^{-1}(q) + u^{-1}(r) \end{aligned}$$

Hence  $u^{-1}(r) = u^{-1}(\tilde{r})$  and so  $r = \tilde{r}$ . This completes the proof up to the lemma.  $\square$

**Lemma 22.**  $\mu : \mathbb{P}_1 \rightarrow \mathbb{C}$  is holomorphic, where

$$\mu[b, c] = \Lambda + \int_{[0:1:0]}^{p_1(b,c)} y^{-1} dx + \int_{[0:1:0]}^{p_2(b,c)} y^{-1} dx + \int_{[0:1:0]}^{p_3(b,c)} y^{-1} dx$$

*Proof.* For all but finitely many  $b \in \mathbb{C}$  the partial derivative

$$\frac{dQ_\Lambda}{dx}(x, y, z)$$

of the polynomial  $Q_\Lambda$  defining  $C_\Lambda$  is nonzero at  $(a, b, 1)$  when  $a$  is a root of the polynomial  $Q_\Lambda(x, b, 1)$  in  $x$ . For such  $a, b$ , the polynomial  $Q_\Lambda(x, b, 1)$  has 3 distinct roots,  $a_1, a_2, a_3$  and

$$p_i = [a_i, b, 1]$$

By the implicit function theorem applied to  $Q_\Lambda(x, y, 1)$  there are open neighborhoods  $U$  and  $V_1, V_2, V_3$  of  $b$  and  $a_1, a_2, a_3$  in  $\mathbb{C}$  and holomorphic functions  $g_i : U \rightarrow V_i$  such that if  $x \in V_i$  and  $y \in U$  then

$$Q_\Lambda(x, y, 1) = 0 \leftrightarrow z = g_i(y).$$

Hence there are holomorphic maps  $\psi_i : U \rightarrow C_\Lambda$  given by

$$\psi_i(w) = [g_i(w), w, 1].$$

We may choose  $V_1, V_2, V_3$  to be disjoint. This means that if  $w \in U$  then  $g_1(w), g_2(w), g_3(w)$  are distinct roots of  $Q_\Lambda(x, w, 1)$  and so

$$p_i(w, 1) = [g_i(w), w, 1] = \psi_i(w).$$

Thus if  $\gamma$  is a path in  $U$  from  $b$  to  $w$  then  $\psi_i \circ \gamma$  is a path in  $C_\Lambda$  from  $p_i(b, 1)$  to  $p_i(w, 1)$  and

$$\int_{\psi_i \circ \gamma} y^{-1} dx = \int_\gamma \frac{g'_i(w)}{w} dw.$$

Thus

$$\mu[w, 1] = \mu[b, 1] + \sum_{i=1}^3 \int_b^w \frac{g'_i(y)}{y} dy$$

where the integrals are over any path. Since  $g'_i(u) = 0$  when  $y = 0$  the functions  $g'_i(y)/y$  are holomorphic on  $U$  so their integrals from  $b$  to  $w$  are holomorphic functions of  $w$  near  $b$ . Thus  $\mu$  is holomorphic in a neighborhood of  $[b, 1]$ . Thus we have shown that  $\mu$  is holomorphic except at possibly finitely many points of  $\mathbb{P}_1$ . By an appendix theorem it now suffices to show that  $\mu$  is continuous, which is left as an exercise.  $\square$