

Lecture 22 Really?!! All Higher

Order Diff Eqns are First Order!!

Office Hours this week: Thursday 2-4pm
891 Evans
(no office hours today)

Friday: Quiz through §6.2

Next week: Happy Thanksgiving!

No sections on Wed, no quiz on Fri.
or Fri

Exer Write following 3rd order IVP
as a first order IVP

$$y''' + 7y' - 3y = \sin(t)$$

$$y(0) = 1, \quad y'(0) = -2, \quad y''(0) = 5$$

Soln Introduce new fns

$$y_1 = y, \quad y_2 = y', \quad y_3 = y''$$

These fns satisfy:

$$1) \quad y_1' = y_2$$

$$y_2' = y_3$$

$$y_3' = -7y_1' + 3y_2 + \sin(t) \\ = -7y_2 + 3y_1 + \sin(t)$$

} 1st
order
eqns.

$$2) \quad y_1(0) = 1, \quad y_2(0) = -2, \quad y_3(0) = 5$$

Organize as matrix eqn:

$$\underline{y} = \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix}$$

$$\underline{y}' = \begin{bmatrix} y_2 \\ y_3 \\ -7y_2 + 3y_1 + \sin(t) \end{bmatrix}$$

$$y(0) = \begin{bmatrix} 1 \\ -2 \\ 5 \end{bmatrix}$$

$$A = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 3 & -7 & 0 \end{bmatrix}$$

$$\underline{y}' = A\underline{y} + \underline{f}$$

$$\underline{f} = \begin{bmatrix} 0 \\ 0 \\ \sin(t) \end{bmatrix}$$

Def A normal form for a lin syst
of diff eqns is an eqn

$$y' = Ay + \underline{f}$$

$n \times n$ -matrix of fns
 n -vectors of fns.

Exer Rewrite the following 2nd order syst
in normal form

$$x_1'' + 6\sin(t)x_1 - 2x_2' = 0$$

$$x_2'' - e^{3t}x_1 = 0$$

Soln Set $y_1 = x_1, y_2 = x_1'$

$$y_3 = x_2, y_4 = x_2'$$

These fns satisfy:

$$y_1' = y_2$$

$$y_2' = -6\sin(t)y_1 + 2y_4$$

$$y_3' = y_4$$

$$y_4' = e^{3t}y_1$$

$$y = \begin{bmatrix} y_1 \\ y_2 \\ y_3 \\ y_4 \end{bmatrix}$$

$$y' =$$

$$\begin{bmatrix} 0 & 1 & 0 & 0 \\ -6\sin(t) & 0 & 0 & 2 \\ 0 & 0 & 0 & 1 \\ e^{3t} & 0 & 0 & 0 \end{bmatrix}$$

y

($\bar{f} = \bar{0}$ homog)

A

Thm There is a unique soln to IVP

$$y' = Ay + \underline{f} \quad y(t_0) = Y_0$$

where A $n \times n$ matrix of fns on (a, b)

\underline{f} n vector of fns on (a, b)

~~with~~ $t_0 \in (a, b)$

and Y_0 n vector of numbers

Usual analysis: V vect sp of n -tuples
of fns

$T: V \rightarrow V$ lin transf

$$T = \begin{bmatrix} \lambda & & & 0 \\ & \ddots & & \\ 0 & & \lambda & \\ & & & \lambda \end{bmatrix} - A$$

Homog eqn: $Ty = 0$

Nonhomog eqn: $Ty = \underline{f}$

Usual strategy:

1) Find basis of solns y_1, \dots, y_n
to homog eqn.

2) Find single soln y_0 to nonhomog eqn

3) Gen soln $y = y_0 + c_1 y_1 + \dots + c_n y_n$

Finally, to solve IVP:

Need: $y(t_0) = y_0(t_0) + c_1 y_1(t_0) + \dots + c_n y_n(t_0) = Y_0$

Thus need: $c_1 y_1(t_0) + \dots + c_n y_n(t_0) = Y_0 - y_0(t_0)$

Solve lin syst:

$$\left[\begin{array}{c|ccc} 1 & & & \\ \hline y_1(t_0) & \dots & y_n(t_0) & \\ \hline \end{array} \right] \begin{bmatrix} c_1 \\ \vdots \\ c_n \end{bmatrix} = \begin{bmatrix} 1 \\ Y_0 - y_0(t_0) \\ 1 \end{bmatrix}$$

Wronskian $W(t) = \det \begin{bmatrix} y_1(t) & \dots & y_n(t) \\ y_1'(t) & \dots & y_n'(t) \\ \vdots & & \vdots \\ y_1^{(n-1)}(t) & \dots & y_n^{(n-1)}(t) \end{bmatrix}$

Fact: $W(t) \neq 0$ all $t \iff y_1, \dots, y_n$
lin indep solns
of homog eqn

Exer Show if matrix eqn comes from
an n th order eqn, then Wronskian
is exactly Wronskian of previous lectures.

Now specialize to constant coeff.

$$y' = Ay + \underline{f}$$

$n \times n$ matrix
of numbers

Focus on homog eqn

$$y' = Ay$$

Think of this as
e-vector/e-value
eqn with $\lambda = \frac{d}{dt}$!

Thm If \underline{u} is an e-vector of A with e-value r then $e^{rt} \underline{u}$ is a soln

$$\text{to } \underline{y}' = A \underline{y}.$$

Proof Check $A(e^{rt} \underline{u}) = e^{rt} A \underline{u}$

$$= e^{rt} \cdot r \cdot \underline{u} = \frac{d}{dt}(e^{rt} \underline{u}) /$$

Then Suppose $\underline{u}_1, \dots, \underline{u}_n$ is a basis of
e-vectors of A with e-values

r_1, \dots, r_n (for example A is symmetric)

then $e^{r_1 t} \underline{u}_1, \dots, e^{r_n t} \underline{u}_n$ is a basis of solns

$$\text{to } \underline{y}' = A \underline{y}$$

Exer Find gen soln to $y' = Ay$ where

$$1) A = \begin{bmatrix} 0 & 0 \\ 0 & 5 \end{bmatrix}$$

Soln e-values 0, 5
e-vectors $\begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix}$

$$y = c_1 e^{0t} \begin{bmatrix} 1 \\ 0 \end{bmatrix} + c_2 e^{5t} \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$2) A = \begin{bmatrix} 2 & -3 \\ 1 & -2 \end{bmatrix}$$

Soln: e-values 1, -1
e-vectors $\begin{bmatrix} 3 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \end{bmatrix}$

$$y = c_1 e^{1 \cdot t} \begin{bmatrix} 3 \\ 1 \end{bmatrix} + c_2 e^{-1 \cdot t} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

Bold, abstract alternative method:

This will always work even if there is not a basis of e-vectors.
Price to pay... possibly computationally intensive

Recall: soln to $y' = ry$ is

$$y = e^{rt} c, \quad c \text{ number}$$

In general: soln to $y' = Ay$ is

$$y = e^{At} \underline{c}, \quad \underline{c} \text{ vector of numbers}$$

Def. $e^{At} = I + At + \frac{(At)^2}{2!} + \frac{(At)^3}{3!} + \dots$

Check $\frac{d}{dt} (e^{At}) = \frac{d}{dt} (I) + \frac{d}{dt} (At) + \frac{d}{dt} \left(\frac{(At)^2}{2!} \right) + \dots$

$$= 0 + A + A^2t + \frac{A^3t^2}{2!} + \dots$$

$= A e^{At} !$
so $e^{At} \subseteq$ solves eqn.!

Exer Solve $y' = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} y$

Soln $e^{At} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} + \begin{pmatrix} 0 & -t \\ 0 & 0 \end{pmatrix} + \begin{pmatrix} -\frac{t^2}{2} & 0 \\ 0 & -\frac{t^2}{2} \end{pmatrix} + \dots$

$$= \begin{bmatrix} \cos(t) & -\sin(t) \\ \sin(t) & \cos(t) \end{bmatrix}$$

Basis of solns

$$\begin{bmatrix} \cos(t) \\ \sin(t) \end{bmatrix}, \begin{bmatrix} -\sin(t) \\ \cos(t) \end{bmatrix}$$