

Good morning and welcome to
Lecture 15 Fun Applications!

Today: Office Hours 1-3pm 736 Evans

Friday: Quiz through § 5.5

Tuesday 10/27: midterm review 12:30-2pm
2040 VLSB

Thursday 10/29: Midterm 2 through § 6.3

Warmup Exer (why diagonalizing is useful in an example)

Let $A = \begin{bmatrix} 1 & 6 \\ 5 & 2 \end{bmatrix}$. Calculate A^{2015}

Soln Last lecture we diagonalized A .

e-values: $7, -4$

e-vectors: $v_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}, v_2 = \begin{bmatrix} -6 \\ 5 \end{bmatrix}$

$$\underline{\text{Observe}} \quad A^{2015} = \begin{pmatrix} P & D & P^{-1} \\ \zeta \leftarrow B & \zeta \leftarrow B & \zeta \leftarrow B \end{pmatrix}^{2015}$$

$$= P D^{2015} P^{-1} \\ = \zeta \leftarrow B \quad \zeta \leftarrow B$$

$$= \begin{bmatrix} 1 & -\frac{6}{5} & 1 \\ 1 & 1 & 0 \\ 1 & 1 & 0 \end{bmatrix} \begin{pmatrix} (7)^{2015} \\ 0 \\ (-4)^{2015} \end{pmatrix} \begin{bmatrix} (\frac{5}{11}) \\ -1 & 1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ \frac{6}{5} \end{bmatrix}$$

Conclusion

$$A_{2015} = \left(\frac{5}{11} \right)$$

$$\left[\begin{array}{l} 7_{2015} - \left(-\frac{6}{5} \right) (-4)_{2015} \\ 7_{2015} - (-4)_{2015} \end{array} \right] \left[\begin{array}{l} \left(\frac{6}{5} \right) 7_{2015} + \left(-\frac{6}{5} \right) (-4)_{2015} \\ \left(\frac{6}{5} \right) 7_{2015} + (-4)_{2015} \end{array} \right]$$

Nice Criterion for diagonalizing:

(sufficient but not necessary)

Thm If A $n \times n$ matrix ~~has~~ ^{has} k distinct
e-values $\lambda_1, \dots, \lambda_k$ then the
corresponding e-vectors v_1, \dots, v_k
are lin indep

If $k=n$, then e-vectors v_1, \dots, v_n
form a basis

Proof: By contradiction: suppose not

take \underline{v}_ℓ with ℓ smallest such that

$$\underline{v}_\ell = a_1 \underline{v}_1 + \dots + a_{\ell-1} \underline{v}_{\ell-1} \quad (*)$$

So $\underline{v}_1, \dots, \underline{v}_{\ell-1}$ are lin indep.

Apply A to (*)

(**)

$$A \underline{v}_\ell = \lambda_\ell \underline{v}_\ell = a_1 \lambda_\ell \underline{v}_1 + \dots + a_{\ell-1} \lambda_{\ell-1} \underline{v}_{\ell-1}$$

Form $\lambda_2 \cdot (*) - (**)$

$$\underline{0} = a_1(\lambda_2 - \lambda_1)\underline{v}_1 + \dots + a_{l-1}(\lambda_2 - \lambda_{l-1})\underline{v}_{l-1}$$
$$\underline{v}_1, \dots, \underline{v}_{l-1} \text{ lin indep} \Rightarrow a_i(\lambda_2 - \lambda_i) = 0$$

all i .

Case 1 all $a_i = 0 \checkmark$ then $(*) \Rightarrow \underline{v}_l = \underline{0}$
but \underline{v}_l is e-vector

Case 2 some $a_i \neq 0$ so $\lambda_2 - \lambda_i = 0 \checkmark$
since λ_i all distinct.

Exer $T: \mathcal{P}_2 \rightarrow \mathcal{P}_2$, $T = \frac{d}{dx} + x \frac{d}{dx}$

Is there a basis of \mathcal{P}_2 such that matrix $[T]_{\mathcal{B}}$ is diagonal?

Soln In std basis $\mathcal{E} = \{1, x, x^2\}$

$$[T]_{\mathcal{E}} = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 1 & 2 \\ 0 & 0 & 2 \end{bmatrix}$$

T can be diagonalized
e-values = 0, 1, 2 so diagonalized by T

Summary of strategy to diagonalize A

1) Find eigenvalues: find roots of $\chi_A(t)$

2) Find e-spaces: $E_\lambda = \text{Null}(A - \lambda I)$
find basis v_1, \dots, v_k

3) Form D and P: $D = \begin{bmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_n \end{bmatrix}$

What can go wrong? (There are no bugs in math only features!)

1) $\chi_A(t)$ does not have enough solns

ex: $A = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$ $\chi_A(t) = t^2 + 1$

2) $\dim E_\lambda <$ multiplicity of λ
as a root of $\chi_A(t)$

So don't have enough e-vectors

Problem 2) is insurmountable



But you can
take 110!

... Jordan form

What to do about Problem 1) ?

Fundamental Thm of Algebra

Every polynomial $P(t)$ completely factors if we allow complex roots

$$P(t) = c(t - \lambda_1)(t - \lambda_2) \dots (t - \lambda_n)$$

λ_i roots, possibly repeating

$$\underline{\text{Ex}} \quad \chi_A(t) = t^2 + 1 = (t - i)(t + i)$$

If we accept complex numbers,
then we can always fix
Problem 1) /

What if we're Alexander that's and
don't accept complex numbers?

What's the best we can do with a 2×2
matrix A with complex e -values?

We can find basis $B = \{w_1, w_2\}$
so that

$$C = P^{-1} A P$$

$B \leftarrow C \quad C \leftarrow B$

with $C = \begin{bmatrix} a & b \\ -b & a \end{bmatrix}$ rotation

Scaling \rightarrow $= \begin{bmatrix} r & 0 \\ 0 & r \end{bmatrix} \begin{bmatrix} \cos\theta & \sin\theta \\ -\sin\theta & \cos\theta \end{bmatrix}$

$r = \sqrt{a^2 + b^2}$, $a = r \cos\theta$, $b = r \sin\theta$

How to find $B = \{\underline{w}_1, \underline{w}_2\}$, C ?

Find complex e-values λ_+ , λ_-

and complex e-vectors \underline{v}_+ , \underline{v}_-

Observe $\lambda_+ = a + ib$, $\lambda_- = a - ib$

~~Here~~
Here are a, b !

$\underline{w}_1 = \text{Re}(\underline{v}_+)$, $\underline{w}_2 = \text{Im}(\underline{v}_+)$

Application of e-values / e-vectors :

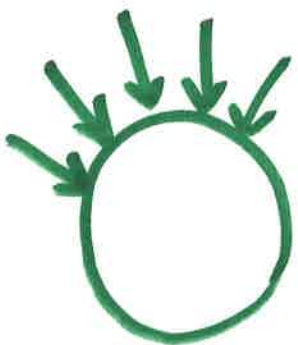
Google's PageRank algorithm

Problem to solve : ranking webpages

Old school : rank by occurrences
of keywords.

New idea: rank by importance

function of 1) popularity



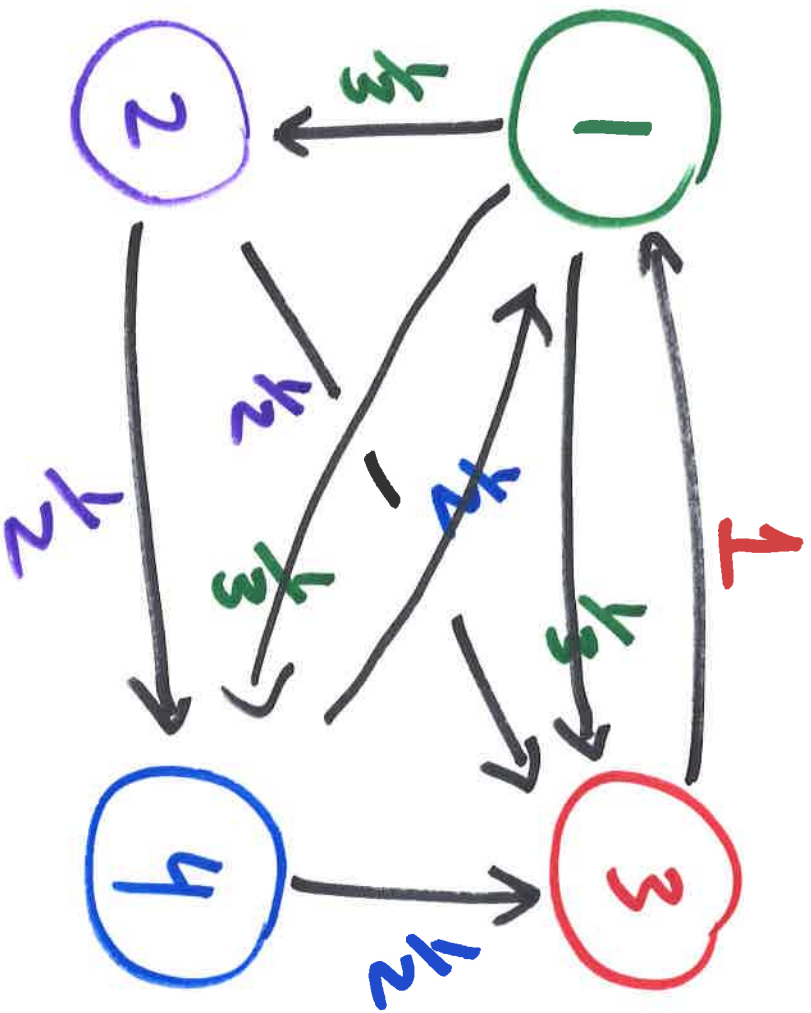
2) authority: importance
of those linking

If we have an internet I and

a webpage $i \in I$, we'll write

x_i for its importance

Mini - Internet I



Organize weights into matrix

$$A = \begin{bmatrix} 0 & 0 & 1 & \frac{1}{2} \\ \frac{1}{3} & 0 & 0 & 0 \\ \frac{1}{3} & \frac{1}{2} & 0 & \frac{1}{2} \\ \frac{1}{3} & \frac{1}{2} & 0 & 0 \end{bmatrix}$$

Organize importance into vector

$$\underline{X} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix}$$

Solve eqn:

$$A \underline{x} = \underline{x} \quad |$$

"Importance is weighted sum
of importances of everyone
linking to you."

In example: e-vector with
e-value $\lambda = 1$

$$\bar{x} = \begin{bmatrix} 12 \\ 4 \\ 9 \\ 6 \end{bmatrix}$$

Page Rank: 1, 3, 4, 2