

§9. Entropy

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An entropy of a map/flow, roughly speaking, is a nonnegative number which describes how "complicated" the map/flow is, in the sense of the growth of the number of "different" trajectories of length n as $n \rightarrow \infty$.

Very roughly speaking,

$$\# \begin{matrix} \text{(different trajectories)} \\ \text{of length } \leq n \end{matrix} \sim \exp(\text{entropy} \cdot n)$$

§9.1. Topological entropy

Let us start with the case of maps (not necessarily invertible, for now):

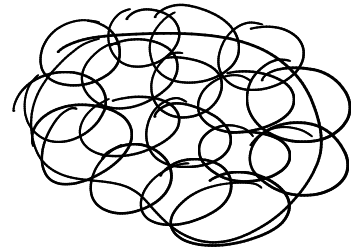
- (X, d) compact metric space
- $\varphi: X \rightarrow X$ continuous map

Before we bring in φ ,
we discuss various ways of
counting how many ε -sized balls
pack in X etc.:

Defn Let (X, d) be a compact
metric space. Let $\varepsilon > 0$. Define:

• $S_d(\varepsilon) =$ the minimal number N
of points $x_1, \dots, x_N \in X$ such that

$$X \subset \bigcup_{j=1}^N B_d(x_j, \varepsilon)$$



where $B_d(a, \varepsilon) = \{x \in X : d(x, a) \leq \varepsilon\}$
is a metric ball

• $D_d(\varepsilon) =$ the minimal number N of
sets $B_1, \dots, B_N \subset X$ such that $X \subset \bigcup_{j=1}^N B_j$
and $\text{diam } B_j \leq \varepsilon \quad \forall j$

Here $\text{diam } B = \sup \{d(x, y) \mid x, y \in B\}$

• $N_d(\varepsilon) =$ the maximal

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number N of points $x_1, \dots, x_N \in X$
such that $d(x_j, x_k) > \varepsilon \quad \forall j \neq k.$

Each of these is a slightly different way of counting how many different points X has if we look at "resolution" ε (w.r.t. the metric d)

They are all roughly equivalent:

Lemma 1 We have $(1) D_d(2\varepsilon) \leq S_d(\varepsilon) \leq D_d(\varepsilon)$ and

$(2) N_d(2\varepsilon) \leq S_d(\varepsilon) \leq N_d(\varepsilon)$

Proof $S_d(\varepsilon) \leq D_d(\varepsilon)$:

if $X \subset \bigcup_{j=1}^{D_d(\varepsilon)} B_j$, $\text{diam } B_j \leq \varepsilon$, then

take any $x_j \in B_j$ & we have $X \subset \bigcup_{j=1}^{D_d(\varepsilon)} B(x_j, \varepsilon)$

(as $B_j \subset B(x_j, \varepsilon)$)

$$\underline{D_d(2\varepsilon) \leq S_d(\varepsilon):}$$

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$$\text{if } X \subset \bigcup_{j=1}^{S_d(\varepsilon)} B(x_j, \varepsilon)$$

then $X \subset \bigcup_{j=1}^{S_d(\varepsilon)} B_j$ where $B_j := B(x_j, \varepsilon)$
and $\text{diam}(B_j) \leq 2\varepsilon$.

$$\underline{S_d(\varepsilon) \leq N_d(\varepsilon):}$$

if $x_1, \dots, x_{N_d(\varepsilon)}$
are ε -separated (i.e. $d(x_j, x_k) > \varepsilon \forall j \neq k$)
then $X \subset \bigcup_{j=1}^{N_d(\varepsilon)} B(x_j, \varepsilon)$.

Indeed, otherwise $\exists x \in X : d(x_j, x) > \varepsilon \forall j$

but then $x, x_1, \dots, x_{N_d(\varepsilon)}$ would be ε -separated.
(contradicting the maximality of $N_d(\varepsilon)$)

$$\underline{N_d(2\varepsilon) \leq S_d(\varepsilon):}$$

if $x_1, \dots, x_{N_d(2\varepsilon)}$
are 2ε -separated, then $\forall j \neq k$,
 x_j and x_k cannot lie in the same ball
of radius ε . So we need at least $N_d(2\varepsilon)$
balls of radius ε to cover
the points $x_1, \dots, x_{N_d(2\varepsilon)}$. \square

Remark: (won't be useful right away...)

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if X is a (compact) manifold,
 $\dim X = r$, then as $\varepsilon \rightarrow 0$ we have

$$S_d(\varepsilon) \sim D_d(\varepsilon) \sim N_d(\varepsilon) \sim \varepsilon^{-r}$$

in the sense that $\exists C > 0 \forall \varepsilon < 1$

$$\frac{1}{C} \varepsilon^{-r} \leq S_d(\varepsilon) \leq C \varepsilon^{-r} \dots$$

Now we bring in the map $\varphi: X \rightarrow \mathbb{S}$.

Fix a metric d on X and for $n \geq 0$

define the refined metric

$$d_n(x, y) = \max_{j=0}^{n-1} d(\varphi^j(x), \varphi^j(y))$$

$$= \max(d(x, y), d(\varphi(x), \varphi(y)), \dots, d(\varphi^{n-1}(x), \varphi^{n-1}(y)))$$

That is, $d_n(x, y) \leq \varepsilon$ if

$$\forall j=0, \dots, n-1, d(\varphi^j(x), \varphi^j(y)) \leq \varepsilon$$

i.e. the trajectories $\varphi^j(x), \varphi^j(y)$
stay ε -close for $0 \leq j < n$.

(If we are looking at a "resolution" ε then such trajectories look the same)

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Define $D_\varphi(\varepsilon, n) = D_{d_n}(\varepsilon)$

= minimal number N of sets

B_1, \dots, B_N such that

$X \subset \bigcup_{\ell=1}^N B_\ell$ (they cover X) and

$\forall x, y \in B_\ell, d_n(x, y) \leq \varepsilon$

(each B_ℓ has all trajectories ε -close for time $0 \leq j \leq n-1$)

The quantity D_φ is useful to us because it is submultiplicative w.r.t. n :

Lemma 2 We have $\forall n, m \geq 0$

$$D_\varphi(\varepsilon, n+m) \leq D_\varphi(\varepsilon, n) D_\varphi(\varepsilon, m)$$

Proof Assume that

$(B_\ell)_{\ell=1}^{D_\varphi(\varepsilon, n)}$, $(C_r)_{r=1}^{D_\varphi(\varepsilon, m)}$ are

collections of subsets such that

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$$X \subset \bigcup_{\ell} B_{\ell}, \quad X \subset \bigcup_r C_r,$$

$$\text{and } \text{diam}_{d_n}(B_{\ell}) \leq \varepsilon \quad \forall \ell, r$$
$$\text{diam}_{d_m}(C_r) \leq \varepsilon$$

Define the sets $(A_{\ell r})_{\substack{1 \leq \ell \leq D_{\ell}(\varepsilon, n) \\ 1 \leq r \leq D_r(\varepsilon, m)}}$

$$\text{as } A_{\ell r} := B_{\ell} \cap \varphi^{-n}(C_r).$$

That is, $x \in A_{\ell r}$ if $x \in B_{\ell}$ AND $\varphi^n(x) \in C_r$.

Roughly speaking, ℓ encodes what happens to the trajectory $\varphi^k(x)$ for $0 \leq k < n$ and r encodes what happens for $n \leq k < n+m$.

We have $X \subset \bigcup_{\ell, r} A_{\ell r}$, so

we are done once we prove that

$$\forall x, y \in A_{\ell r}, \quad d_{n+m}(x, y) \leq \varepsilon.$$

But here

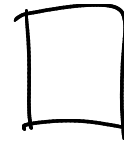
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$$d_{n+m}(x, y) = \max(d(x, y), \dots, d(\varphi^{n+m-1}(x), \varphi^{n+m-1}(y))) \\ = \max(d_n(x, y), d_m(\varphi^n(x), \varphi^n(y)))$$

and $d_n(x, y) \leq \varepsilon$ (as $x, y \in B_\varepsilon$)

and $d_m(\varphi^n(x), \varphi^n(y)) \leq \varepsilon$ (as $\varphi^n(x), \varphi^n(y) \in C_r$).



We now want to describe the asymptotics of $D_\varphi(\varepsilon, n)$ as $n \rightarrow \infty$.

I.e. how many "different at resolution ε " trajectories of length n are there?

We are hoping for something like

$$D_\varphi(\varepsilon, n) \sim e^{h_\varepsilon n} \text{ for some } h_\varepsilon \geq 0.$$

So we should define

$$h_\varepsilon := \lim_{n \rightarrow \infty} \frac{\log D_\varphi(\varepsilon, n)}{n}.$$

Here the limit exists

since $\log D_\varphi(\varepsilon, n)$ is subadditive (by Lemma 2) and by

Fekete's Lemma Assume $a_n \in \mathbb{R}$

is a subadditive sequence, i.e.

$$a_{n+m} \leq a_n + a_m \quad \forall n, m \geq 1.$$

Then $\lim_{n \rightarrow \infty} \frac{a_n}{n} = \inf_n \frac{a_n}{n}.$

Proof Certainly $\liminf_{n \rightarrow \infty} \frac{a_n}{n} \geq \inf_n \frac{a_n}{n}.$

So it suffices to show that

$$\limsup_{n \rightarrow \infty} \frac{a_n}{n} \leq \inf_m \frac{a_m}{m}.$$

For that it is enough to show that $\forall m,$

$$\limsup_{n \rightarrow \infty} \frac{a_n}{n} \leq \frac{a_m}{m}$$

Take large n & write $n = q \cdot m + r, \quad 0 \leq r < m, \quad q \geq 0.$

Then $a_n \leq q \cdot a_m + a_r.$

$$\text{So } \frac{a_n}{n} \leq \frac{q \cdot a_m + a_r}{n} \leq$$

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$$\leq \frac{q^m}{n} \cdot \frac{a_m}{m} + \frac{a_r}{n}$$

But as $n \rightarrow \infty$, we have $\frac{a_r}{n} \rightarrow 0$

(only finitely many options for r)

and $\frac{q^m}{n} \rightarrow 1$. So

$\limsup_{n \rightarrow \infty} \frac{a_n}{n} \leq \frac{a_m}{m}$ as needed. \square

So now we have defined

$$h_\varepsilon := \lim_{n \rightarrow \infty} \frac{1}{n} \log D_\varphi(\varepsilon, n).$$

Of course this can depend on ε ,
e.g. if $\text{diam}(X) \leq \varepsilon$ then $h_\varepsilon = 0$
(as $D_\varphi(\varepsilon, n) = 1$)

Note that h_ε is a decreasing function of $\varepsilon > 0$:

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if $\varepsilon_1 < \varepsilon_2$ then $\forall n$
 $D_\varphi(\varepsilon_1, n) \geq D_\varphi(\varepsilon_2, n)$
and thus $h_{\varepsilon_1} \geq h_{\varepsilon_2}$.

Defn The topological entropy of φ is defined as

$$h_{\text{top}}(\varphi) = \lim_{\varepsilon \rightarrow 0^+} h_\varepsilon = \sup_{\varepsilon > 0} h_\varepsilon,$$

$$\text{i.e. } h_{\text{top}}(\varphi) = \lim_{\varepsilon \rightarrow 0^+} \lim_{n \rightarrow \infty} \frac{1}{n} \log D_\varphi(\varepsilon, n).$$

Note: $h_{\text{top}}(\varphi)$ does not change if we replace d by an equivalent metric (exercise)

Lemma 3 ① If φ^k , $k \geq 1$,
is k -th iterate of φ , then

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$$h_{\text{top}}(\varphi^k) = k \cdot h_{\text{top}}(\varphi)$$

② If φ is a homeomorphism
(i.e. φ^{-1} exists & is continuous)
then $h_{\text{top}}(\varphi^{-1}) = h_{\text{top}}(\varphi)$.

Proof ① Assume that $B \subset X$

is such that $\text{diam}_{d_{nk, \varphi}}(B) \leq \varepsilon$,
i.e. $\forall j=0, 1, \dots, nk-1$, we have $\forall x, y \in B$

$$d(\varphi^j(x), \varphi^j(y)) \leq \varepsilon.$$

Then $\forall \ell=0, \dots, n-1$ we have $\forall x, y \in B$

$$d(\varphi^{k\ell}(x), \varphi^{k\ell}(y)) \leq \varepsilon \quad (\text{putting } j=k\ell).$$

So $\text{diam}_{d_{n, \varphi^k}}(B) \leq \varepsilon$.

This shows $D_{\varphi^k}(\varepsilon, n) \leq D_{\varphi}(\varepsilon, nk)$.

$$\text{Thus } \frac{1}{n} \log D_{\varphi^k}(\varepsilon, n) \leq \frac{k}{nk} \log D_{\varphi}(\varepsilon, nk) \quad \left| \begin{array}{l} 18.118 \\ 9-13 \end{array} \right.$$

Which (taking $n \rightarrow \infty$) gives

$$h_{\varepsilon}(\varphi^k) \leq k h_{\varepsilon}(\varphi)$$

and thus (taking $\varepsilon \rightarrow 0$)

$$h_{\text{top}}(\varphi^k) \leq k \cdot h_{\text{top}}(\varphi).$$

On the other hand, if we fix $\varepsilon > 0$ then there exists $\tilde{\varepsilon} > 0$

such that $\forall x, y \in X,$

$$d(x, y) \leq \tilde{\varepsilon} \Rightarrow d(\varphi^r(x), \varphi^r(y)) \leq \varepsilon$$

$$\forall r = 0, \dots, k-1$$

(by uniform continuity of φ).

If $B \subset X$ has $\text{diam}_{d_n, \varphi^k} B \leq \tilde{\varepsilon},$

i.e. $\forall x, y \in B \quad \forall \ell = 0, \dots, n-1$

$$d(\varphi^{k\ell}(x), \varphi^{k\ell}(y)) \leq \tilde{\varepsilon},$$

then $\forall x, y \in B \quad \forall j=0, 1, \dots, nk-1$ 18.118
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we get $d(\varphi^j(x), \varphi^j(y)) \leq \varepsilon$

by writing $j = kl + r$, $0 \leq r < k$
 $0 \leq l < n$

and using that $d(\varphi^{kl}(x), \varphi^{kl}(y)) \leq \tilde{\varepsilon}$.

It follows that

$$\text{diam}_{d_{nk, \varphi}}(B) \leq \varepsilon.$$

Thus $D_{\varphi}(\varepsilon, nk) \leq D_{\varphi^k}(\tilde{\varepsilon}, n)$

and (taking $\frac{1}{n} \log(\dots)$ & $n \rightarrow \infty$)

$$k \cdot h_{\varepsilon}(\varphi) \leq h_{\tilde{\varepsilon}}(\varphi^k)$$

which gives (taking sup over $\varepsilon > 0$)

$$k \cdot h_{\text{top}}(\varphi) \leq h_{\text{top}}(\varphi^k).$$



② Assume now that φ is a homeomorphism. We show that

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$$h_{\text{top}}(\varphi^{-1}) \leq h_{\text{top}}(\varphi)$$

which is enough since we can apply the same argument to φ^{-1} .

It is enough to prove that $\forall \varepsilon > 0, n$ we have

$$D_{\varphi^{-1}}(\varepsilon, n) \leq D_{\varphi}(\varepsilon, n).$$

Let $N := D_{\varphi}(\varepsilon, n)$ and

$B_1, \dots, B_N \subset X$ be such that $X \subset \bigcup_e B_e$

and $\text{diam}_{d_{n, \varphi}}(B_e) \leq \varepsilon$.

Put $\tilde{B}_e := \varphi^{n-1}(B_e)$. Then

$X \subset \bigcup_e \tilde{B}_e$ and $\text{diam}_{d_{n, \varphi^{-1}}}(\tilde{B}_e) \leq \varepsilon$:

indeed, if $\tilde{x}, \tilde{y} \in \tilde{B}_e$ then

$\tilde{x} = \varphi^{n-1}(x), \tilde{y} = \varphi^{n-1}(y)$ for some $x, y \in B_e$

and $\text{diam}_{d_{n, \varphi}}(B_e) \leq \varepsilon \Rightarrow d(\varphi^j(x), \varphi^j(y)) \leq \varepsilon$
 $\forall j = 0, \dots, n-1$

$\Rightarrow d(\varphi^{-k}(\tilde{x}), \varphi^{-k}(\tilde{y})) \leq \varepsilon \quad \forall k = 0, \dots, n-1$

as $\varphi^{-k}(\tilde{x}) = \varphi^{n-1-k}(x) \dots \Rightarrow d_{n, \varphi^{-1}}(\tilde{x}, \tilde{y}) \leq \varepsilon$.

It follows that $D_{\varphi^{-1}}(\varepsilon, n) \leq N$
and finishes the proof. \square

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For flows, entropy is defined similarly
to maps: if $\varphi^t: X \rightarrow X$ is a flow then
we consider the metrics $d_T(x, y) =$
 $= \sup_{0 \leq t < T} d(\varphi^t(x), \varphi^t(y))$, and we
can define $D_{\varphi}(\varepsilon, T)$ and $h_{\text{top}}(\varphi)$.

§9.2. Examples of entropy computation

① $X = S^1 = \mathbb{R}/\mathbb{Z}$, $\varphi(x) = x + r \pmod{\mathbb{Z}}$

for some fixed $r \in \mathbb{R}$:

We have $d_n(x, y) = \max_{j=0}^{n-1} d(\varphi^j(x), \varphi^j(y))$
 $= d(x, y)$ (where d is the standard metric on S^1)

Since $d(\varphi^j(x), \varphi^j(y)) = d(x, y) \forall j$.

Thus $D_{\varphi}(\varepsilon, n)$ is independent of n , so
 $h_{\varepsilon} = 0 \forall \varepsilon > 0$, and thus $h_{\text{top}}(\varphi) = 0$.

This works any time φ is an isometry.

② $X = \mathbb{S}^1$, $\varphi(x) = 2x \pmod{\mathbb{Z}}$. 18.118
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We use the following

Lemma If $\varepsilon \leq \frac{1}{4}$ and $x, y \in \mathbb{S}^1$
then $d_n(x, y) \leq \varepsilon \iff d(x, y) \leq \frac{\varepsilon}{2^{n-1}}$.

Proof We need to show

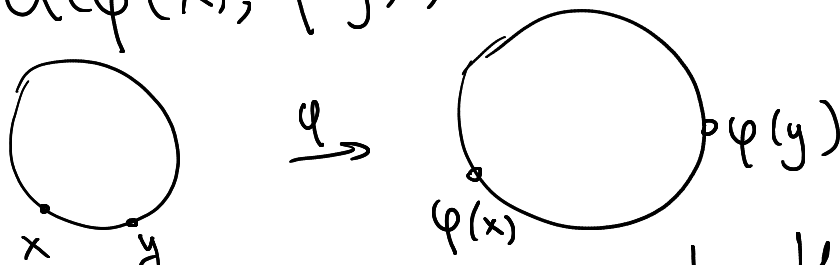
$$d(x, y) \leq \frac{\varepsilon}{2^{n-1}} \iff \forall j=0, \dots, n-1, d(\varphi^j(x), \varphi^j(y)) \leq \varepsilon.$$

\implies : follows from the Lipschitz bound
 $d(\varphi(x), \varphi(y)) \leq 2 d(x, y) \quad \forall x, y \in \mathbb{S}^1.$

\impliedby : we have $\forall x, y \in \mathbb{S}^1$:

if $d(x, y) \leq \frac{1}{4}$ then

$$d(\varphi(x), \varphi(y)) = 2 d(x, y):$$



Thus, if $d_n(x, y) \leq \varepsilon \leq \frac{1}{4}$ then

$$d(\varphi^j(x), \varphi^j(y)) = 2^j d(x, y) \quad \forall j = 0, \dots, n-1$$

(by induction on j)

and thus $d(x, y) \leq \frac{\varepsilon}{2^{n-1}}$.



Given the lemma, we see that

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$\forall \varepsilon \leq \frac{1}{4}$, $\forall n$, we have

$D_\varphi(\varepsilon, n) =$ minimal number N
of sets B_1, \dots, B_N s.t. $S^1 \subset \bigcup_e B_e$

and $\text{diam}_d(B_e) \leq \frac{\varepsilon}{2^{n-1}}$.

\uparrow
diameter w.r.t. the usual metric on \mathbb{R}/\mathbb{Z} .

This gives $D_\varphi(\varepsilon, n) = \left\lceil \frac{2^{n-1}}{\varepsilon} \right\rceil$

Then $h_\varepsilon = \lim_{n \rightarrow \infty} \frac{\log D_\varphi(\varepsilon, n)}{n} = \log 2$

So $\boxed{h_{\text{top}}(\varphi) = \log 2}$

③ Hyperbolic toral automorphisms:

$X = \mathbb{T}^2 = \mathbb{R}^2 / \mathbb{Z}^2$, $\varphi(x) = Ax \text{ mod } \mathbb{Z}^2$,

$A \in \text{SL}(2, \mathbb{Z})$ hyperbolic.

Let λ, λ^{-1} be the eigenvalues of A ,
with $|\lambda| > 1$.

Fix some $x \in X$ and $n \geq 0$, 18.118
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as well as small enough $\varepsilon > 0$.

We want to understand the ball

$$\{y \in X \mid d_n(x, y) \leq \varepsilon\}.$$

Certainly, it's contained in the small ball

$B_d(x, \varepsilon)$, so we can locally
identify \mathbb{T}^2 with \mathbb{R}^2 here.

Then we can define the stable/unstable
distances $d_s(x, y)$, $d_u(x, y)$ as follows:

if $v_u, v_s \in \mathbb{R}^2$ are unit length
vectors s.t. $Av_u = \lambda v_u$, $Av_s = \lambda^{-1} v_s$,

then write $x - y = a_u v_u + a_s v_s$

for some small $a_u, a_s \in \mathbb{R}$ and put

$$d_u(x, y) := |a_u|$$

$$d_s(x, y) := |a_s|.$$

Similarly to the Lemma in Example 2, 18.118
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we have

Lemma If ε is small enough then
 $\exists C$ (independent of ε) such that
 $\forall x, y \in X \quad \forall n \geq 0$ we have

$$\textcircled{a} \quad d_n(x, y) \leq \frac{\varepsilon}{C \cdot |\lambda|^n}, \quad d_S(x, y) \leq \frac{\varepsilon}{C}$$

$$\Downarrow$$

$$d_n(x, y) \leq \varepsilon$$

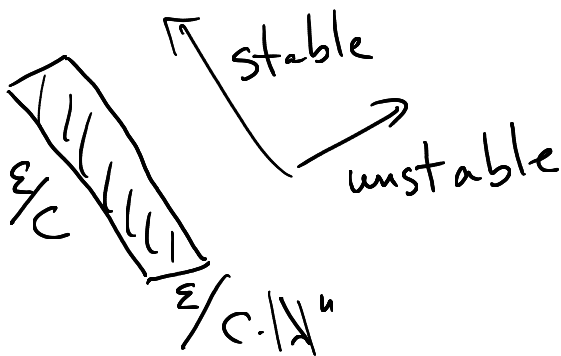
and

$$\textcircled{b} \quad d_n(x, y) \leq \varepsilon \Rightarrow$$

$$\Rightarrow d_u(x, y) \leq \frac{C\varepsilon}{|\lambda|^n}, \quad d_S(x, y) \leq C\varepsilon.$$

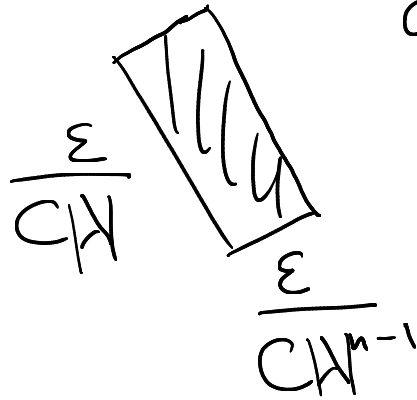
Proof: \textcircled{a} Let's look at the set of

$$y \in X: d_u(x, y) \leq \frac{\varepsilon}{C \cdot |\lambda|^n}, \quad d_S(x, y) \leq \frac{\varepsilon}{C} : (*)$$



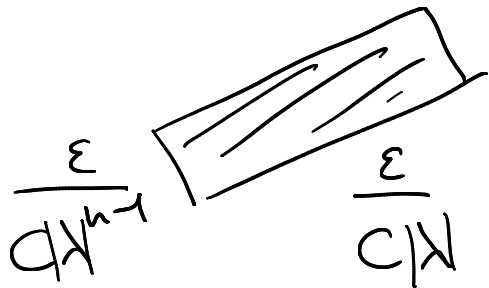
Looks like a rectangle.

Apply φ to this rectangle \rightarrow 18.118
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 \rightarrow we set another rectangle



and so on up until φ^{n-1} (this set)

is



yet another rectangle.

(Note: no wrapping around the torus
 as ϵ is small)
 Each of these sets has diameter $\leq \epsilon$
 if C is large enough.

So if y satisfies (*) then

$$d_n(x, y) \leq \epsilon.$$

⑥ Assume now that $d_n(x, y) \leq \varepsilon$.

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Then we can see (similarly to the pictures in part (a), and using that ε is small) that for $j=0, \dots, n-2$

$$d_u(\varphi^{j+1}(x), \varphi^{j+1}(y)) = |\lambda| \cdot d_u(\varphi^j(x), \varphi^j(y))$$

$$d_s(\varphi^{j+1}(x), \varphi^{j+1}(y)) = |\lambda|^{-1} \cdot d_s(\varphi^j(x), \varphi^j(y)).$$

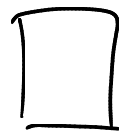
Indeed, write $x-y$ as a linear combination of v_u, v_s and apply the linear map A . (No wrapping around since ε is small).

$$\text{So then: } d_u(\varphi^{n-1}(x), \varphi^{n-1}(y)) = |\lambda|^{n-1} \cdot d_u(x, y)$$

$$\text{And } d_u(\varphi^{n-1}(x), \varphi^{n-1}(y)) \leq C d(\varphi^{n-1}(x), \varphi^{n-1}(y)) \leq C\varepsilon.$$

$$\text{So } d_u(x, y) \leq \frac{C\varepsilon}{|\lambda|^{n-1}}.$$

$$\text{And } d_s(x, y) \leq C d(x, y) \leq C\varepsilon.$$



Now, $D_\varphi(\varepsilon, n)$ is the minimal number N of sets B_1, \dots, B_N s.t. $X \subset \bigcup_e B_e$ and

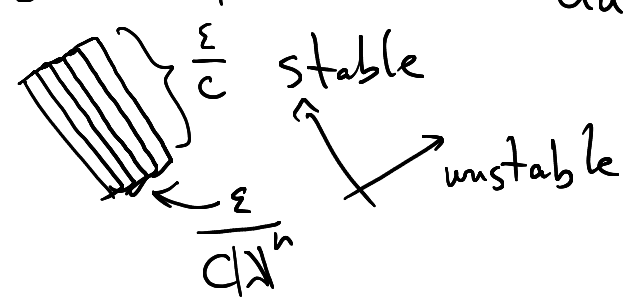
$$x, y \in B_e \Rightarrow d_n(x, y) \leq \varepsilon.$$

• Each such B_e is contained in a rectangle (for any $x \in B_e$) $\{y : d_u(x, y) \leq \frac{C\varepsilon}{|\Lambda|^n}, d_s(x, y) \leq C\varepsilon\}$ which has area $\leq \frac{C' \cdot \varepsilon^2}{|\Lambda|^n}$.

So $N \geq \frac{|\Lambda|^n}{C' \cdot \varepsilon^2}$

• On the other hand, if C' is large enough then we can find $N \leq \frac{C' |\Lambda|^n}{\varepsilon^2}$

rectangles B_1, \dots, B_N , $X \subset \bigcup_e B_e$ such that $\text{diam}_{d_u}(B_e) \leq \frac{\varepsilon}{C|\Lambda|^n}$, $\text{diam}_{d_s}(B_e) \leq \frac{\varepsilon}{C}$



and thus $\text{diam}_{d_n}(B_e) \leq \varepsilon$.

$$\text{So, } \frac{|\lambda|^n}{C' \varepsilon^2} \leq D_\varphi(\varepsilon, n) \leq \frac{C' |\lambda|^n}{\varepsilon^2}.$$

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$$\text{Then } h_\varepsilon = \lim_{n \rightarrow \infty} \frac{\log D_\varphi(\varepsilon, n)}{n} = \log |\lambda|.$$

$$\text{Thus } \boxed{h_{\text{top}}(\varphi) = \log |\lambda|}.$$

④ Geodesic flow $\varphi^t: X \rightarrow X$
 where $X = SM$ and (M, g)
 is a hyperbolic surface.

A similar argument to ③
 shows that $\boxed{h_{\text{top}}(\varphi) = 1}$

where we use that the expansion/
 contraction rate of the flow
 on the unstable/stable spaces
 is equal to 1: $d\varphi^t \cdot U_\pm = e^{\mp t} U_\pm$.

We finish this subsection with the following

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Fact: if $\varphi: X \rightarrow X$ is an

Anosov map and

$N(T) = \#$ of periodic points of φ of period $\leq T$

then $N(T) \underset{T \rightarrow \infty}{\sim} e^{h_{\text{top}}(\varphi) \cdot T}$,

i.e. $\lim_{T \rightarrow \infty} \frac{1}{T} \log N(T) = h_{\text{top}}(\varphi)$.

A similar statement holds for Anosov flows

We won't give a proof;

see [Katok-Hasselblatt, §18.5]